

THE KAVERY ENGINEERING COLLEGE*(An Autonomous Institution)***UG/PG DEGREE END SEMESTER THEORY EXAMINATIONS, APRIL-MAY 2026****Fourth Semester****Electronics and Communication Engineering****EC3492 – DIGITAL SIGNAL PROCESSING****Regulations - 2021****Duration : 3 Hrs****Maximum : 100 Marks****PART – A(ANSWER ALL QUESTIONS) (Marks 10*2=20)**

Q.No	Questions	BLT	CO	Marks
1.	Find the DFT of $Y(k) = \{1, 0, 1, 0\}$	L2	1	2
2.	Obtain circular convolution of the following sequence $x(n) = \{1, 2, 3\}$ and $h(n) = \{1, -2, 2\}$	L2	1	2
3.	How many number of additions and multiplications are required to realize a system $H(z)$ having M zeros and N poles in direct form I realization?	L1	2	2
4.	State the need of prewarping.	L2	2	2
5.	List the features of Hamming window.	L1	3	2
6.	What is the disadvantage of Fourier series method?	L1	3	2
7.	Define deadband of the filter	L2	4	2
8.	What is meant by quantization step size?	L2	4	2
9.	What is meant by upsampling?	L2	5	2
10.	Write any two applications of adaptive filter.	L1	5	2

PART – B (ANSWER ALL QUESTIONS) (Marks 5*16 = 80)

Q.No	Questions	BLT	CO	Marks
11. a	Find $X(k)$ using DIT FFT algorithm for $x(n) = \{0, 1, 2, 3, 4, 5, 6, 7\}$	L3	1	16
	Or			
b	Perform the linear convolution of the following sequence by 1. Overlap Add method 2. Overlap save method $X(n) = \{1, 2, 3, -1, -2, -3, 4, 5, 6\}$ $h(n) = \{2, 1, -1\}$	L3	1	16
12. a	Design the Chebyshev filter using bilinear transformation for the following specification. Find the order of the filter. $0.8 \leq H(e^{j\omega}) \leq 1 \quad \text{for } 0 \leq \omega \leq 0.2\pi$ $ H(e^{j\omega}) \leq 0.2 \quad \text{for } 0.6\pi \leq \omega \leq \pi$	L3	2	16
	Or			
b	Obtain the direct form I, direct form II, cascade and parallel form realization for the system $y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)$	L3	2	16
13. a	Design an ideal FIR Low pass filter using rectangular window for $N=7$ having frequency response as given below: $H_d(e^{j\omega}) = \begin{cases} 1 & \frac{\pi}{4} \leq \omega \leq \frac{3\pi}{4} \\ 0 & \text{otherwise} \end{cases}$	L3	3	16
	Or			
b	Use frequency sampling method to design a FIR low pass filter with $\omega_c = \pi/4$ for $N=15$. Plot the magnitude and phase response.	L3	3	16

14.	a	i	Two first order filters are connected in cascade whose system function of the individual sections are $H_1(z) = \frac{1}{1-0.5z^{-1}} \quad H_2(z) = \frac{1}{1-0.4z^{-1}}$ Determine the overall output noise power if b=3 (excluding sign bit).	L3	4	8
		ii	An LTI system is characterized by the difference equation $y(n) = 0.87y(n-1) + x(n)$ Determine the limit cycle behavior and deadband of the system when $x(n)=0$ and $y(-1)=0.61$. Assume the product is quantized to 4 bits, excluding sign bit by rounding. Or	L3	4	8
	b	i	Describe in detail about the effect of quantization error due to truncation for fixed point 1's complement and 2's complement number.	L3	4	8
		ii	The output of an A/D converter is applied to a digital filter with system function $H(z) = \frac{0.29z}{z-0.64}$. Find the output noise power for the digital filter, when the input signal is quantized to 11 bits.	L3	4	8
15.	a		Elucidate the cascading of sample rate converters.	L2	5	16
			Or			
	b		Discuss in detail the principle of fixed and floating-point principles in Digital signal processors.	L2	5	16
